Argo program IDG SOLOII Engineering/CONFIG Table Manual/Decoder Version 1.0 Last updated December 18th, 2013 Adapted from SOLO2_Xformat_v1.0_12Sep11 John Gilson Applicable ROMS: SBE602 30Jan11, 08Jun11			
	ID=0xe0, Engineering message in first diagnostic dive at start of mission		
Byte	Contents		
0	ID/Mission phase = 0xe0		
1-2	Number of bytes= 76 = 0x4C		
3-4	empty		
5-6	empty		
7-8	empty		
9-10	empty		
11-12	empty		
13-14	DP->Vcpu: CPU battery voltage counts (0.01V), on surface at start of Xmit after data processed ARGO TECHNICAL NAME: VOLTAGE_BatteryCPUStartXmit_volts		
15-16	DP->Vpmp: Pump battery counts at surface (0.01V) ARGO TECHNICAL NAME: VOLTAGE_BatterySurfaceNoLoad_volts		
17-18	DP->Vple: Pump battery counts at end of last pump on ascent (0.01V) ARGO TECHNICAL NAME: VOLTAGE_BatteryPumpLastValueAsAscends_volts		
19-20	Btvac: Built-in-Test vacuum at startup (0.01 inHg)		
21-22	DP->Air[1]: Pressure case vacuum before filling bladder on surface (0.01 inHg) ARGO TECHNICAL NAME: PRESSURE_InternalVacuumAtStartSurface_inHg		
23-24	DP->Air[2]: Pressure case vacuum after filing bladder on surface (0.01 inHg) ARGO TECHNICAL NAME: PRESSURE_InternalVacuumOilBladderFull_inHg		
25-26	DP->ISRID: i.d. of last interupt		
27-28	DP->HPavgl: Average pump motor current taken at start of ascent (LSB=1ma) ARGO TECHNICAL NAME: CURRENT_BatteryAvgPumpOnStartAscent_mA		
29-30	DP->HPmaxl: Maximum pump motor current taken at start of ascent (LSB=1ma) ARGO TECHNICAL NAME: CURRENT_BatteryMaxPumpOnStartAscent_mA		
31-32	Total seconds pumping to get to the surface		
33-34	seconds pumped at the surface		
35-36	DP->P[5]: Surface pressure counts at end of ascent (LSB = 0.04 dbar) ARGO TECHNICAL NAME: PRES_AscentEnd_dbar		
37-38	SPRX: Surface pressure before resetoffset (pertains to BIT) (dbar) ARGO TECHNICAL NAME: PRES_SurfaceOffsetBeforeReset_dbar orReset_4mBarResolution_dbar		
39-40	SPRXL: Surface pressure after resetoffset (pertains to BIT) (dbar) ARGO TECHNICAL NAME: PRES_SurfaceOffsetAfterReset_dbar orReset_4mBarResolution_dbar		
41-42	diagP[0]: Pressure when "in water" sensed by float after deployment Argo MEASUREMENT_CODE=199		
43-44	diagT[0]: Temperature when "in water" sensed by float after deployment Argo MEASUREMENT_CODE=199		
45-46	diagS[0]: Salinity when "in water" sensed by float after deployment Argo MEASUREMENT_CODE=199		

47-48	Snnscan: # scans recorded by SBD (1 Hz): // -1 (0xFFFF) indicates unable to get scan count from SBE // -2 (0xFFFE) indicates SBE never started so SBE didn't reset scan count before returning an old value ARGO TECHNICAL NAME: TIME_ToAscend_seconds			
49-50	Compacted Sbntry, Sbstrt, Sbstop status (see misspec.h) ((DP->SBntry&0xF) ((DP->SBstrt&0x3)<<2) DP->SBstop&0x3))			
51-52	diagP[1]: Shallowest CTD Pressure reading upon ascent Argo MEASUREMENT_CODE=599			
53-54	diagT[1]: Shallowest CTD Temperature reading upon ascent Argo MEASUREMENT_CODE=599			
55-56	diagS[1]: Shallowest CTD Salinity reading upon ascent Argo MEASUREMENT_CODE=599			
57-58	Btvac: Built-in-Test vacuum at startup (0.01 inHg)			
59-60	BTavgl: Built-in-Test motor current OUT at startup (LSB = 1mA)			
61-62	BTPsec: Built-in-Test pump seconds			
63-64	BTPvac: Built-in-Test pump vacuum (0.01 inHg)			
65-66	BTVple: Built-in-Test pump battery at startup (0.01V)			
67-68	BTVcpu: Built-in-Test CPU battery at startup (0.01V)			
69-70	Exception Flags (see 0xe2 message below)			
71	Vent (air bubble) data: # 0.1 seconds vent motor ran			
72	Vent (air bubble) data: LLD status before and after vent ran			
73-74	AbrtCd = Code for what caused abort_miss			
75	; terminator			

	ID=0xE2, Engineering message in normal dive cycle		
Byte	Contents		
0	ID/Mission phase = 0xe2		
1-2	Number of bytes= $90 = 0x5A$		
3-4	#packets in previous surface session		
5-6	#tries to connect in previous surface session		
7-8	parse_X_reply status in previous surface session		
9-10	ATSBD return status in previous surface session		
11-12	EP->sattime: seconds taken in previous surface session to send all SBD messages		
13-14	DP->Vcpu: CPU battery voltage counts (0.01V), on surface at start of Xmit after data processed ARGO TECHNICAL NAME: VOLTAGE_BatteryCPUStartXmit_volts		
15-16	DP->Vpmp: Pump battery counts at surface (0.01V) ARGO TECHNICAL NAME: VOLTAGE_BatterySurfaceNoLoad_volts		
17-18	DP->Vple: Pump battery counts at end of last pump on ascent (0.01V) ARGO TECHNICAL NAME: VOLTAGE_BatteryPumpLastValueAsAscends_volts		
19-20	DP->Air[0]: Pressure case vacuum during sinking at 50db (0.01 inHg) ARGO TECHNICAL NAME: PRESSURE_InternalVacuumDuringDescent50dbar_inHg		
21-22	DP->Air[1]: Pressure case vacuum before filling bladder on surface (0.01 inHg) ARGO TECHNICAL NAME: PRESSURE_InternalVacuumAtStartSurface_inHg		
23-24	DP->Air[2]: Pressure case vacuum after filing bladder on surface (0.01 inHg) ARGO TECHNICAL NAME: PRESSURE_InternalVacuumOilBladderFull_inHg		
25-26	DP->ISRID: i.d. of last interupt		
27-28	DP->HPavgl: Average pump motor current taken at start of ascent (LSB=1ma) ARGO TECHNICAL NAME: CURRENT_BatteryAvgPumpOnStartAscent_mA		
29-30	DP->HPmaxl: Maximum pump motor current taken at start of ascent (LSB=1ma) ARGO TECHNICAL NAME: CURRENT_BatteryMaxPumpOnStartAscent_mA		
31-32	Total seconds pumping to get to the surface		
33-34	seconds pumped at the surface		
35-36	SPRX: Surface pressure before resetoffset (pertains to previous dive) (dbar) ARGO TECHNICAL NAME: PRES_SurfaceOffsetBeforeReset_dbar orReset_4mBarResolution_dbar		
37-38	SPRXL: Surface pressure after resetoffset (pertains to previous dive (dbar) ARGO TECHNICAL NAME: PRES_SurfaceOffsetAfterReset_dbar orReset_4mBarResolution_dbar		
39-40	diagP[0]: Pressure at the start of ascent ARGO MEASUREMENT_CODE=499		
41-42	diagT[0]: Temperature at diagP[0] ARGO MEASUREMENT_CODE=499		
43-44	diagS[0]: Salinity at diagP[0] ARGO MEASUREMENT_CODE=499		
45-46	Snnscan: # scans recorded by CTD (1 Hz): // -1 (0xFFFF) indicates unable to get scan count from SBE // -2 (0xFFFE) indicates SBE never started so SBE didn't reset scan count before returning an old value ARGO TECHNICAL NAME: TIME_ToAscend_seconds		
47-48	Compacted Sbntry, Sbstrt, Sbstop status (see misspec.h) ((DP->SBntry&0xF) ((DP->SBstrt&0x3)<<2) DP->SBstop&0x3))		

49-50	DP->P[0]: Pressure counts before begin of descent to park (LSB = 0.04 dbar)			
51-52	DP->P[1]: Pressure counts at end of descent to park (LSB = 0.04 dbar)			
53-54	DP->P[2]: Pressure counts at beginning of drift (park) (LSB = 0.04 dbar)			
55-56	DP->P[3]: Pressure counts at end of drift (park) (LSB = 0.04 dbar)			
57-58	DP->P[5]: Surface pressure counts at end of ascent (LSB = 0.04 dbar)			
59-60	DP->PAVG[0]: Average pressure over first half of drift ARGO MEASUREMENT_CODE=296			
61-62	DP->TAVG[0]: Average temperature over first half of drift ARGO MEASUREMENT_CODE=296			
63-64	DP->SAVG[0]: Average salinity over first half of drift ARGO MEASUREMENT_CODE=296			
65-66	DP->PAVG[1]: Average pressure over second half of drift ARGO MEASUREMENT_CODE=296			
67-68	DP->TAVG[1]: Average temperature over second half of drift ARGO MEASUREMENT_CODE=296			
69-70	DP->SAVG[1]: Average salinity over second half of drift ARGO MEASUREMENT_CODE=296			
71-72	DP-> fall_time = seconds from open air valve (surface) to end of sink ~ 100dbar			
73-74	DP-> fall_rate = avg mm/sec while sinking during fall_time to ~100dbar			
75-76	DP->SeekT= tenths of pumping in first seek of drift ARGO TECHNICAL NAME: TIME_PistonRanDuringFirstSeek_seconds			
77-78	DP->SeekP = change of depth (signed 0.1dbar) in first seek ARGO TECHNICAL NAME: PRESSURE_ChangeInFirstSeek_dbar SEEKP is incorrectly stored: This value times 25/4 gives approximate. Or use P[2]-P[1];			
79-80	Exception flags (can be added to)0x0001Valve failed to open0x0002Valve failed to close0x0004Questionable pressure0x0008Antenna was toggled0x0010Antenna switch failure (no satellites even after toggling)0x0020GPS communication error (can talk to GPS unit)0x0080Float took too long to leave the surface (toggled valve)0x1000Valve failure during sinking phase0x2000Valve failure during ascend phase of mission			
81	Vent (air bubble) data: # 0.1 seconds vent motor ran			
82	Vent (air bubble) data: LLD status before and after vent ran			
83-84	SBE P offset (times 800): Cumulative auto-pressure offset correction ARGO TECHNICAL NAME: PRES_SensorAutoAdjustment_dbar			
85-86	PP->SeekSc: # of tenths of seconds pumped to target (park) depth			
87-88	Number of Packets sent this cycle			
89	; terminator			

	ID=0xe3, Engineering message following mission abort		
Byte	Contents		
0	ID/Mission phase = 0xe3		
1-2	Number of bytes= $30 = 0x1e$		
3-4	#packets in previous surface session		
5-6	#tries to connect in previous surface session		
7-8	parse_X_reply status in previous surface session		
9-10	ATSBD return status in last surface session		
11-12	seconds taken in sending last SBD message		
13-14	current CPU battery voltage Counts (0.01V)		
15-16	current pump battery counts (0.01V)		
17-18	DP->Air[1]: pressure case vacuum at beginning of abort (0.01inHg)		
19-20	DP->Air[0]: pressure case vacuum at end of last xmit (previous cycle) (0.01inHg)		
23-24	DP->ISRID: i.d. of last interrupt		
25-26	AbrtCd = code for what caused abort mission 0 = no error 1 = current time is later than RTCabort 2 = unable to WakeOST 3 = unable to Send dive number to SOLOII (LodiveNo) 4 = Iridium ground station commanded to go to abort 5 = Final dive was completed. Mission is done. 6 = Diagnostic dive ailed to get GPS fix, pressure never > dbarGo, or unable to send message to Iridium 7 = pressure sensor failure		
29	; terminator		

	ID=0xf0 Argo cycle configuration (mission)		
Byte	Contents		
3	Data Version: Matches Decoder/Manual to use		
4-5	Target profile depth		
(i)	Argo CONFIG name: CONFIG_ProfilePressure_dbar		
6-7	Target parking depth Argo CONFIG name: CONFIG_ParkPressure_dbar		
8-9	Maximum rise time		
(a)	Argo CONFIG name: CONFIG_AscentToSurfaceTimeOut_hours		
10-11	Target (maximum) fall to parking depth time		
(b)	Argo CONFIG name: CONFIG_DescentToParkTimeOut_hours		
12-13	Maximum fall-from-parking-to-profile depth time		
(c)	Argo CONFIG name: CONFIG_DescentToMaxPresTimeOut_hours		
14-15	Target drift time		
(d)	Argo CONFIG name: CONFIG_ParkTime_hours		
16	Float Type == 0 for SOLOII		
17	Target ascent rate while profiling		
(e)	Argo CONFIG name: CONFIG_TargetAscentSpeed_cm/s		
18-19	Number of Seeks		
(f)	Argo CONFIG name: CONFIG_SeeksToParkPeriods_COUNT		
20-21	Surface Time		
(g)	Argo CONFIG name: CONFIG_SurfaceTimeOut_hours		
min((a),	CONFIG_CycleTime_hours can be computed as (after converting to same units): min((a),(i)/(e))+(b)+(c)+(d)+(f)*(FALLx)+(g) where FALLx is the time between the last two Pressure/Time pairs in the FALL message 0x40. This will be greater than the actual cycle time.		

	Argo program MEASUREMENT_CODEs (MC)			
Code (timing)	SOLO II Variable	Description	Units	
100 (DST)	Cy>0: Fall ID=0x40	First T,P pair [taken as valve opened to leave surface]	Time,P(0.04db)	
199	Cy=0: Eng ID=0xe0	P,T,S triplet taken when float realizes it is under the surface and pumps to return to the surface (Eng ID=0xe0 bytes 41-46)	P(0.04db),T(0.001 °C), S(0.001psu)	
189/190	Cy>0: Fall ID=0x40	All T,P Fall pairs pre-DET not assigned to other MC (189 indicates buoyancy adjustment)	Time,P(0.04db)	
200 (DET)	Cy>0: Fall ID=0x40	Choice of T,P pair that is first within 3% of pressure at beginning of drift (see Eng ID=0xe2 bytes 59-60)	Time,P(0.04db)	
489	Cy=1: Fall ID=0x40 or any cycle without park phase	If n is the number of stabilizations (see Argo ID=0xf0), the T,P n+1 from end of Fall record is a stabilization. Each later T,P pair excluding the last will be an additional stabilization.	Time,P(0.04db)	
239	Cy>1: Fall ID=0x40			
250 (PST)	Cy>0: Fall ID=0x40	Last T,P Fall pair when Park Phase follows	Time,P(0.04db)	
296	Cy>0: Eng ID=0xe2	Drift broken into two averaged halves. Stored in Eng ID=0xe2 bytes 59-70; Time estimated from the last Fall ID=0x40 T,P pair [note: not DET] and first Rise ID=0x50 T,P pair	P(0.04db),T(0.001 °C), S(0.001psu)	
if profile p	ressure > drift pressure	(typical) NOTE: DPST is never defined in SOL	O/SOLOII	
300 (PET)	Cy>0: Rise ID=0x50	First T,P Rise pair [taken as valve opened]	Time,P(0.04db)	
390	Cy>0: Rise ID=0x50	All pre-AST T,P Rise pairs	Time,P(0.04db)	
400 (DDET)	Cy>0: Rise ID=0x50	DDET is determined by a) 2 nd derivative of Rise pair series or b) within 3% of profile depth (see Eng ID=0xe2 bytes 39-40).	Time,P(0.04db)	
490	Cy>0: Rise ID=0x50	All post-DDET/pre-AST T,P Rise pairs	Time,P(0.04db)	
500 (AST)	Cy>0: Rise ID=0x50; Eng ID=0xe2	AST is determined by 2 nd derivative of Rise pair series. P,T,S triplet taken at start of ascent (Eng ID=0xe2 bytes 39-44)	Time,P(0.04db); P(0.04db),T(0.001 °C), S(0.001psu)	
else (Cy=0	or float rises from drift	depth)		
500 (AST)	Cy=0: Rise ID=0x50;	First T,P Rise pair [taken as valve opened]	Time,P(0.04db);	
	Cy>0: Rise ID=0x50; Eng ID=0xe2	AST is determined by 2 nd derivative of Rise pair series. P,T,S triplet taken at start of ascent	Time,P(0.04db); P(0.04db),T(0.001	

		(Eng ID=0xe2 bytes 39-44)	°C), S(0.001psu)
endif			
589/590	Cy>-1: Rise ID=0x50	All T,P Rise pairs post AST excluding last; 589 indicates buoyancy adjustment.	Time,P(0.04db)
599	Cy=0: Eng ID=0xe0	last P,T,S triplet taken before turning off CTD (Eng ID=0xe0 bytes 51-56)	P(0.04db),T(0.001 °C), S(0.001psu)
600 (AET)	Cy>-1: Rise ID=0x50	Last T,P Rise pair	Time,P(0.04db)
703	Cy=0: GPS ID=0x00	GPS Fix	Time, Position
	Cy>0: GPS ID=0x02	GPS Fix	Time, Position
700 (TST) 702 (FMT)	Time in SBD email	Time of first SBD message	Time
704 (LMT) 800 (TET)	Time in SBD email	Time of last SBD message	Time
703	Cy>0: GPS ID=0x01	GPS Fix	Time, Position